

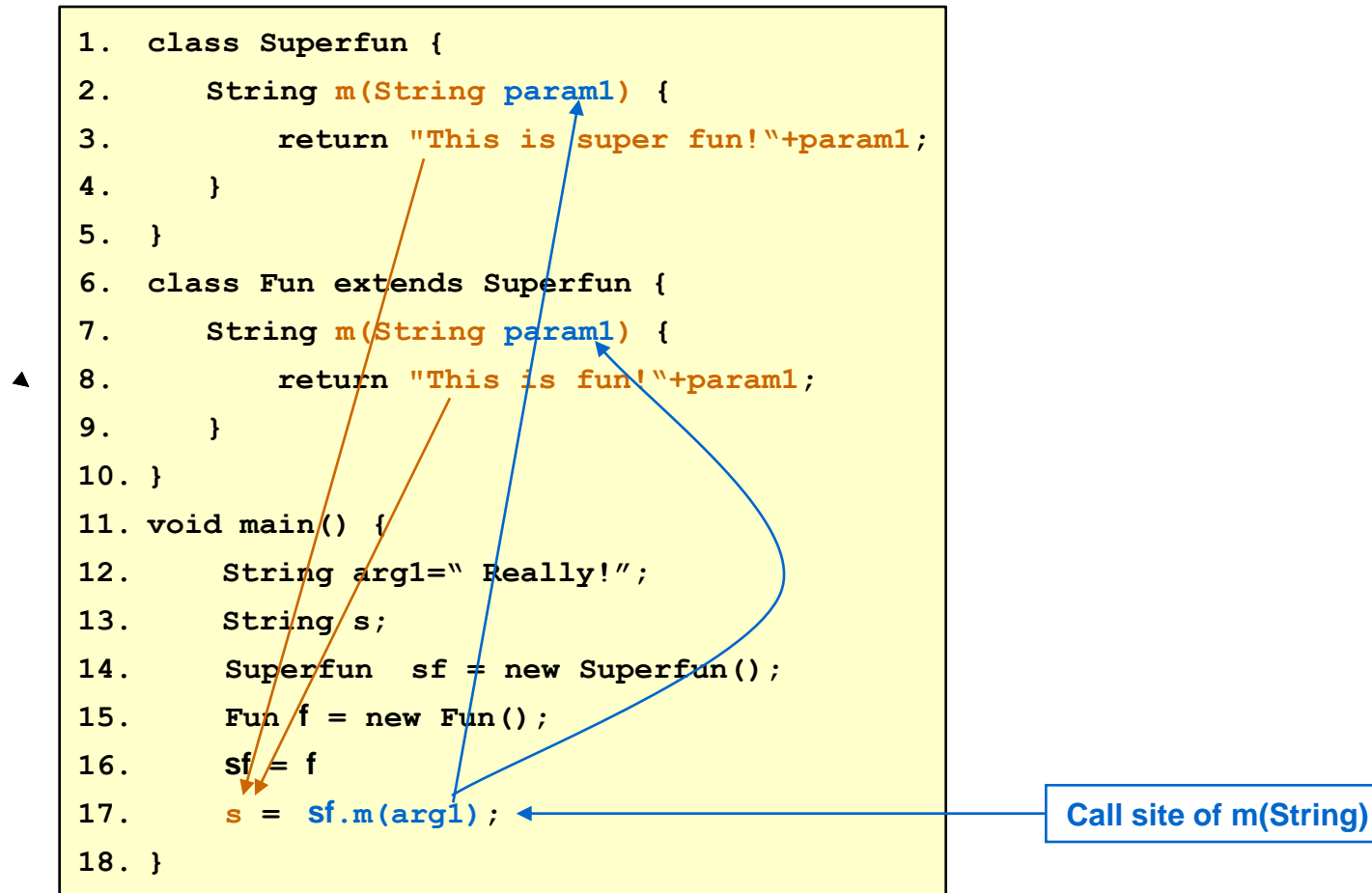
# Interprocedural Analysis

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Aleksandra Biresev  
s6albire@cs.uni-bonn.de

# Interprocedural Analysis

- An interprocedural analysis operates across an entire program, flowing information from **call sites** to their **callees** and vice versa



# Interprocedural Analysis needs a Call Graph

## Sample Program

```
1. class Superfun {
2.     String m() {
3.         return "This is super fun!";
4.     }
5. }
6. class Fun extends Superfun {
7.     String m() {
8.         return "This is fun!";
9.     }
10. }
11. void main() {
12.     Superfun sf = new Superfun();
13.     Fun f = new Fun();
14.     sf=f;
15.     ... = sf.m();
16. }
```

## Call Graph

- Representation of program's calling structure
- Set of nodes and edges such that:
  - ◆ There is one node for each **procedure** in the program
  - ◆ There is one node for each **call site**
  - ◆ If call site **c** may call procedure **p**, then there is an edge from the node for **c** to the node for **p**

# Interprocedural Analysis needs a Call Graph

## Sample Program

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3.        return "This is super fun!";
4.    }
5. }
6.  class Fun extends Superfun {
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12.     Superfun sf = new Superfun();
13.     Fun f = new Fun();
14.     sf=f;
15.     ... = sf.m();
16. }
```

## Statically bound calls

- Call target of each invocation can be determined statically
- Each call site has an edge to exactly one procedure in the call graph
- Examples:
  - ◆ All calls in C, Pascal, ...
  - ◆ Calls of “static” methods in Java

# Interprocedural Analysis needs a Call Graph

## Sample Program

```
1.  class Superfun {
2.    String m() {
3.        return "This is super fun!";
4.    }
5. }
6.  class Fun extends Superfun {
7.    String m() {
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9.    }
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11. void main() {
12.     Superfun sf = new Superfun();
13.     Fun f = new Fun();
14.     sf=f;
15.     ... = sf.m();
16. }
```

receiver expression

## Dynamically bound calls

- Normal case in Java
- We need to know the dynamic type of the message **receiver** before we can determine which method is invoked
- Dynamic type = class form which the **receiver** was instantiated
- How to approximate this information statically?

# Interprocedural Analysis needs a Call Graph

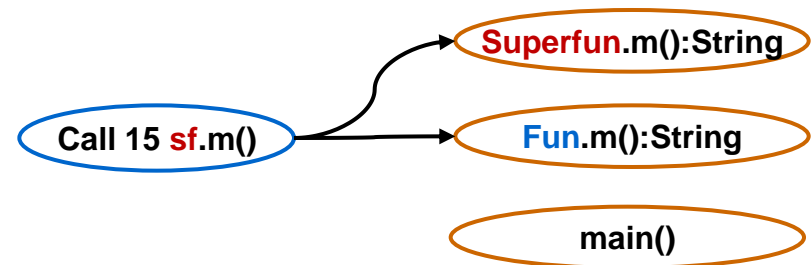
## Sample Program

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5. }
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9. }
10. }
11. void main() {
12.   Superfun sf = new Superfun();
13.   Fun f = new Fun();
14.   sf=f;
15.   ... = sf.m();
16. }
```

receiver expression

## Call Graph based on static type information

- Regard all methods in
  - ◆ static type of receiver
  - ◆ ... and in each subtype
- Static Type
  - ◆ Type declared in the program
- Example
  - ◆ `sf` has static type `Superfun`
- In our example we get



# Why Interprocedural Analysis?

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Using interprocedural analysis a number of important compiler problems can be solved:

- Resolution of Virtual Method Invocations (later in this talk)
  - ◆ More precise Call Graph construction via PTA
- Pointer Alias Analysis
  - ◆ Could two variables eventually point to the same object?
- Parallelization
  - ◆ Will two array references never point to the same array?
- Detection of Software Errors and Vulnerabilities (SQL Injection)
  - ◆ Can user input become executable code?
- The basis of any interprocedural analysis is „Points-to Analysis“

# Outline

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- ✓ Interprocedural Analysis
- ✓ Call Graphs
- Variants of Interprocedural Analysis
- Approaches to Context-Sensitive Interprocedural Analysis
- Points-To-Analysis (PTA)
- Logic programming as an implementation framework



# Variants of Interprocedural Analysis

Context-insensitive

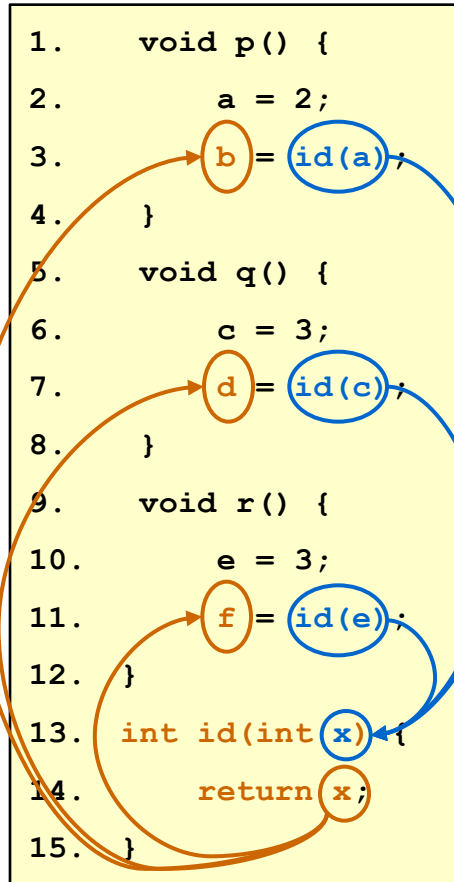
Context-sensitive

Cloning-based

Inline-based

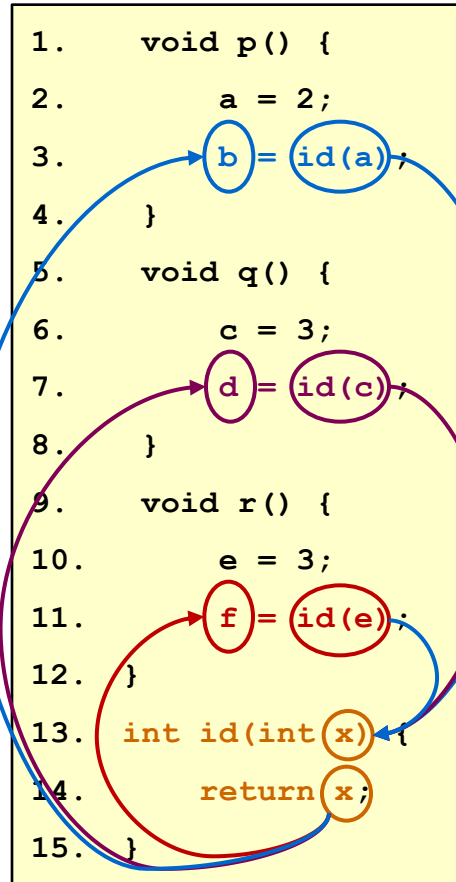
Summary-based

# Interprocedural Analysis ▶ Context-insensitivity



- We do not care about who called the procedure that we currently analyse
  - ◆ E.g. for `id(int)`
- Simple but imprecise
  - ◆ All inputs (values of `a`, `c`, `e`) are merged
  - ◆ Set of potential values for `x` = `{2, 3}`
  - ◆ Imprecision propagates to call sites
  - ◆ We can only discover `{2, 3}` as potential values for `b`, `d` and `f`
- Not so bad when program units are small (few assignments to any variable)
  - ◆ Example: Java code often consists of many small methods

# Interprocedural Analysis ► Context-sensitivity



- We **do** care about who called the procedure that we currently analyse
  - ◆ E.g. **id(a)** or **id(c)** or **id(e)**
- More precise
  - ◆ Inputs are propagated individually for each call
  - ◆ Results are returned only to the related call
  - ◆ We can discover **b=2**, **d=3** or **f=3**.

# Context-sensitivity ► Calling contexts

```
1. void p() {
2.     a = 2;
3.     b = id(a);
4. }
5. void q() {
6.     c = 3;
7.     d = id(c);
8. }
9. void r() {
10.    e = 3;
11.    f = id(e);
12. }
13. int id(int x) {
14.    return add_id(x);
15. }
16. int add_id(int x) {
17.    return x;
18. }
```

- Context
  - ◆ Summary of the sequence of calls that are currently on the run-time stack
- Call string
  - ◆ Sequence of call sites for the calls on the stack
- Call site
  - ◆ Identified by its line number
- Example
  - ◆ Call sequence `id(a)` → `add_id(x)` summarized as call string `(3,14)`
  - ◆ Call strings on this slide: `(3, 14)`, `(7,14 )`, `(11,14)`
  - ◆ Call strings on previous slide: `(3)`, `(7)`, `(11)`

# Approaches to context-sensitive analysis

## ► Cloning-Based

```
1. void p() {
2.     a=2;
3.     b=id1(a);
4. }
5. void q() {
6.     c=3;
7.     d=id2(c);
8. }
9. void r() {
10.    e=3;
11.    f=id3(e);
12. }
```

←--- Not cloned (not called)  
Call clones of id(int)

Clones of id(int)  
Call clones of add\_id(int)

Clones of add\_id(int)

```
14. int id1(int x) {
15.     return add_id1(x);
16. }
17. int id2(int x) {
18.     return add_id2(x);
19. }
20. int id3(int x) {
21.     return add_id3(x);
22. }
```

```
23. int add_id1(int x) {
24.     return x;
25. }
26. int add_id2(int x) {
27.     return x;
28. }
29. int add_id3(int x) {
30.     return x;
31. }
```

- Each procedure is cloned once for each relevant context
- Then context-insensitive analysis of the code resulting from cloning / inlining
- Problem
  - ◆ Exponentially many contexts in the worst case!
  - ◆ Exponentially many clones

# Approaches to context-sensitive analysis

## ► Inlining-Based

```
1. void p() {
2.     a=2;
3.     b=a;
4. }
5. void q() {
6.     c=3;
7.     d=c;
8. }
9. void r() {
10.    e=3;
11.    f=e;
12. }
```

### Inlined body of id(a)

←----- after expanding id(int)  
by inlining add\_int()

### Inlined body of id(c)

←----- after expanding id(int)  
by inlining add\_int()

### Inlined body of id(e)

←----- after expanding id(int)  
by inlining add\_int()

```
14. int id(int x) {
15.     return x;
16. }
```

### Inlined body of add\_id(x)

```
23. int add_id(int y) {
24.     return y;
25. }
```

- Rather than physically cloning, recursively inline body of called procedure at the call
  - ◆ Simplifications possible
- In reality, we do not need to clone the code, neither to inline
  - See talk of Saad

# Approaches to context-sensitive analysis

## ► Summary-Based

```
void p() {
    a = 2;
    b = id(a);
}

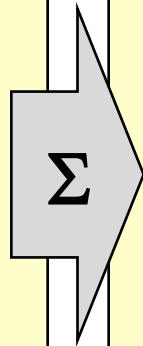
void q() {
    c = 3;
    d = id(c);
}

void r() {
    e = 3;
    f = id(e);
}

int id(int x) {
    return add_id(x);
}

int add_id(int x) {
    return x;
}
```

a) Original



```
void p() {
    a=2;
    b=id_a2();
}

void q() {
    c=3;
    d=id_a3();
}

void r() {
    e=3;
    f=id_a3();
}

int id_a2() {
    return 2;
}

int id2_a3() {
    return 3;
}
```

b) Summaries for 2 different parameter values of id()

- Each procedure is represented by a concise description ("summary") that encapsulates some observable behavior of the procedure
- The primary purpose of the summary is to avoid reanalyzing a procedure's body at every call site
- The analysis consists of two parts:
  - ◆ A top-down phase that propagates caller information (parameter values) to compute results of the callees
  - ◆ A bottom-up phase that computes a "transfer function" to summarize the effect of a procedure

# Points-to Analysis (PTA)

Also known as „Pointer Analysis“





# Pointer Analysis / Points-to Analysis (PTA)

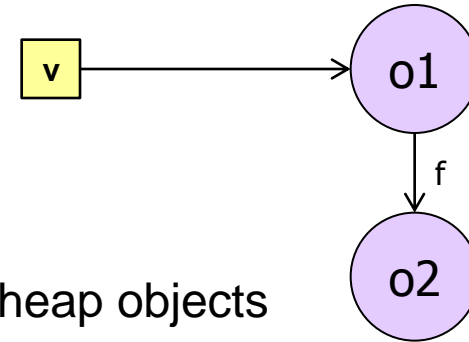
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- Special form of data flow analysis
  - ◆ Not interested in primitive values but only in object references / pointers
- Question: „To which objects can a variable refer?“
- PTA is at the heart of any interprocedural analysis
  - ◆ Because it improves the precision of the call graph

# Pointer Analysis ► Objects flow to Variables

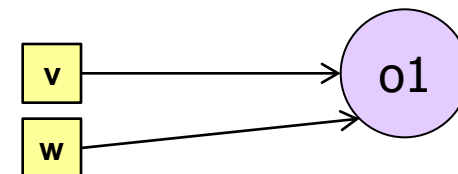
- Stack variables 
  - ◆ point to heap objects

- Heap objects 
  - ◆ may have fields that are references to other heap objects



- A heap object is named by the statement that creates it
  - ◆ We assume each statement is on a separate line and name the objects by the line number of their creation statement
  - ◆ Example

- `T v = new T; // o1 = obj created on line 1`
- `w = v; // now w also points to o1`

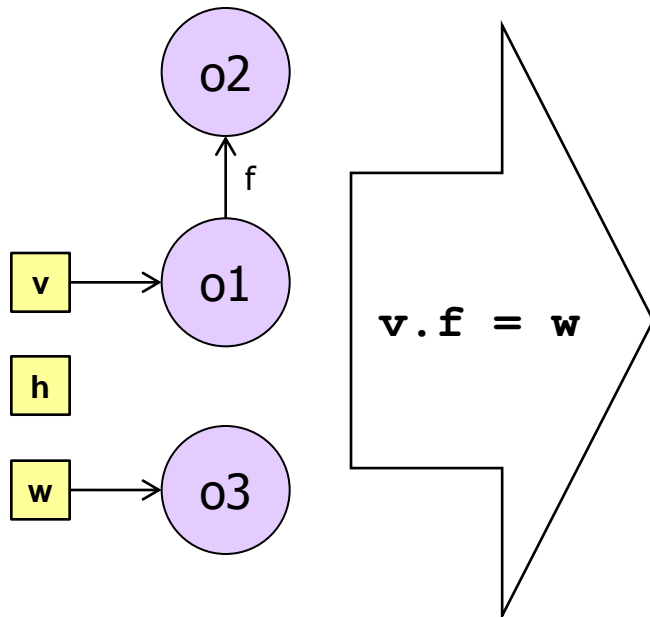


- Note many run-time objects may have the same name
  - ◆ The above code might be executed multiply (many calls to it or loop)

# Pointer Analysis ► Objects flow through Fields

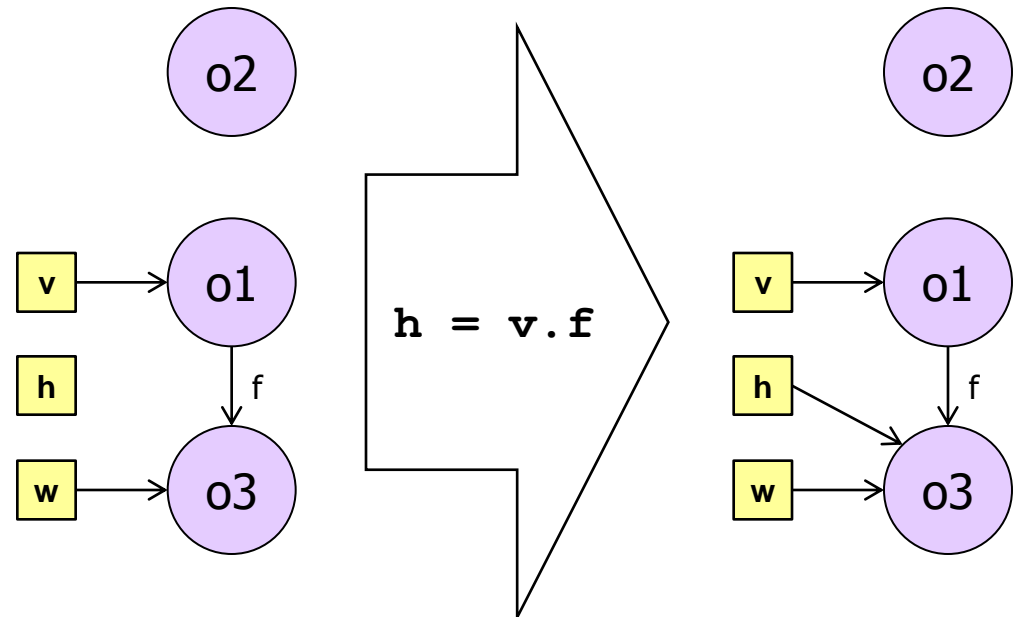
## Putfield

- $v.f = w$  makes the  $f$  field of the object pointed to by  $v$  point to what  $w$  points to



## Getfield

- $h = v.f$  makes  $h$  point to the object pointed to by the  $f$  field of the object pointed to by  $v$



# Call Graph Construction

## Sample Program

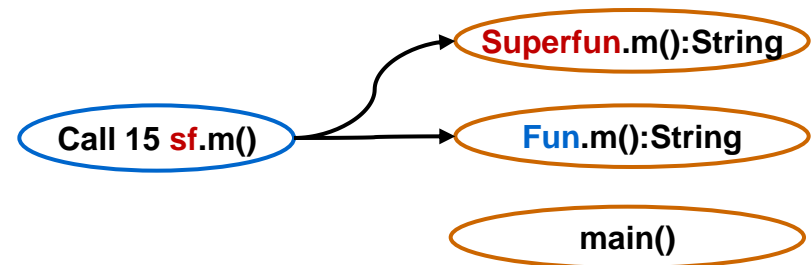
```
1. class Superfun {
2.   String m()
3.     return "This is super fun!";
4. }
5. }
6. class Fun extends Superfun {
7.   String m()
8.     return "This is fun!";
9. }
10. }
11. void main() {
12.   Superfun sf = new Superfun();
13.   Fun f = new Fun();
14.   sf=f;
15.   ... = sf.m();
16. }
```

receiver expression

## Call Graph based on static type information

- Regard all methods in
  - ◆ static type of receiver
  - ◆ ... and in each subtype

- In our example we get



# Call Graph Construction: Precise

## Sample Program

```
1. class Superfun {
2.     String m() {
3.         return "This is super fun!";
4.     }
5. }
6. class Fun extends Superfun {
7.     String m() {
8.         return "This is fun!";
9.     }
10. }
11. void main() {
12.     Superfun sf = new Superfun();
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14.     sf=f;
15.     ... = sf.m();
16. }
```

receiver expression

## Call Graph based on Points-To-Analysis (PTA)

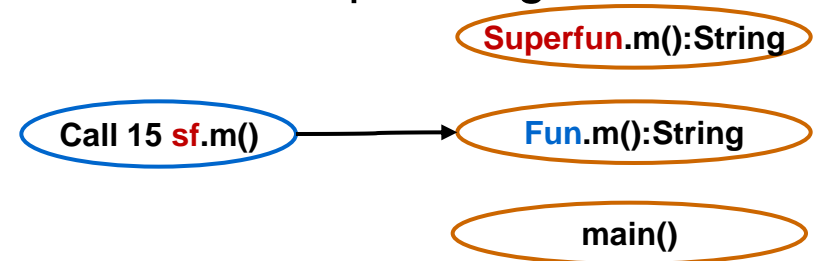
- Statically determine objects referred to by the receiver

After line 12.: `sf` points to `Obj 12 : Superfun`

After line 13.: `f` points to `Obj 13 : Fun`

After line 14.: `sf` points to `Obj 13 : Fun`

- Only regard methods in the classes of these objects!
- In our example we get



# Logic-based Points-to Analysis

Expressing analyses as Prolog rules

# Logical Representation

- Logic allows integration of different aspects of a flow problem
  - ◆ Example: `reach(d,x,i)` = "definition `d` of variable `x` can reach point `i`."
- Example: Assignment
  - ◆ For the assignment statement "`v=w`" in the analysed code, there is a fact / tuple "`assign(v,w)`" in the relation "`assign(To,From)`"
  - ◆ JTransformer: "`assignT(Id, B, M, v, w)`" stands for "The assignment `v=w` occurs in the block `B` of method `M` and has the internal identity `Id`".
- Notational convention
  - ◆ Instead of using relations for the various statement forms, we shall simply use the quoted statement itself to stand for the fact representing the statement → Abstraction from particular fact representation
  - ◆ Example: "`v=w`" instead of "`assign(v,w)`" or "`assignT(Id, B, M, v, w)`"
  - ◆ In "`O: V = new T`" `O` represents the label (line number) of the statement

# Example: Iterative algorithm- round 1

pts(a, o2)

pts(b, o7)

Program code:

```
1.  T p(T x) {
2.    T a = new T;
3.    a.f = x;
4.    return a;
5.  }
6.  void main() {
7.    T b = new T;
8.    b = p(b);
9.    b = b.f;
10. }
```

Derivation rules:

```
1. pts(V,O) :- "O: V = new T".
2. pts(V,O) :- "V=W", pts(W,O) .
3. pts(V,O) :- "V=W.F", alias(W,X) "X.F=V2", pts(V2,O) .
4. alias(W,X) :- pts(W,O) , pts(X,O) .
```



# Example: Iterative algorithm- round 2

pts(a, o2)  
pts(b, o7)  
-----  
pts(x, o7)

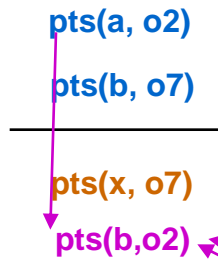
Program code:

```
1. T p(T x) {  
2.   T a = new T;  
3.   a.f = x;  
4.   return a;  
5. }  
6. void main() {  
7.   T b = new T;  
8.   b = p(b);  
9.   b = b.f;  
10. }
```

Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
2. `pts(V,O) :- "V=W", pts(W,O) .`
3. `pts(V,O) :- "V=W.F", alias(W,X) "X.F=V2", pts(V2,O) .`
4. `alias(W,X) :- pts(W,O) , pts(X,O) .`

# Example: Iterative algorithm- round 2



Program code:

```
1.  T p(T x) {  
2.    T a = new T;  
3.    a.f = x;  
4.    return a;  
5.  }  
6.  void main() {  
7.    T b = new T;  
8.    b = p(b);  
9.    b = b.f;  
10. }
```

Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
2. `pts(V,O) :- "V=W", pts(W,O) .`
3. `pts(V,O) :- "V=W.F", alias(W,X) "X.F=V2", pts(V2,O) .`
4. `alias(W,X) :- pts(W,O) , pts(X,O) .`

# Example: Iterative algorithm- round 3

pts(a, o2)  
pts(b, o7)  
-----  
pts(x, o7)  
pts(b,o2)  
↓  
pts(x, o2)

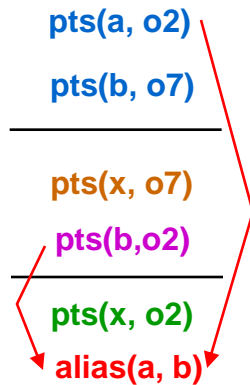
Program code:

```
1.  T p(T x) {  
2.    T a = new T;  
3.    a.f = x;  
4.    return a;  
5.  }  
6.  void main() {  
7.    T b = new T;  
8.    b = p(b);  
9.    b = b.f;  
10. }
```

Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
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4. `alias(W,X) :- pts(W,O), pts(X,O).`

# Example: Iterative algorithm- round 3



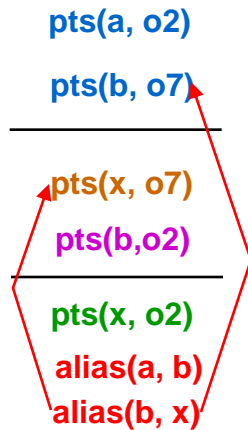
Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
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Program code:

```
1.  T p(T x) {
2.    T a = new T;
3.    a.f = x;
4.    return a;
5.  }
6.  void main() {
7.    T b = new T;
8.    b = p(b);
9.    b = b.f;
10. }
```

# Example: Iterative algorithm- round 3



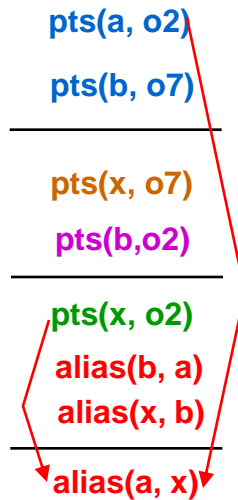
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Program code:

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3.    a.f = x;
4.    return a;
5.  }
6.  void main() {
7.    T b = new T;
8.    b = p(b);
9.    b = b.f;
10. }
```

# Example: Iterative algorithm- round 4



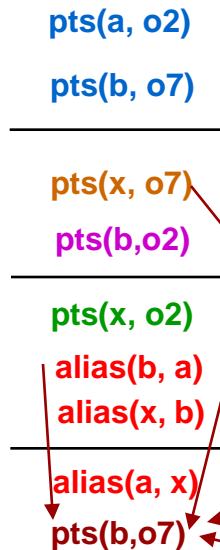
Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
2. `pts(V,O) :- "V=W", pts(W,O) .`
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4. `alias(W,X) :- pts(W,O) , pts(X,O) .`

Program code:

```
1.  T p(T x) {
2.    T a = new T;
3.    a.f = x;
4.    return a;
5.  }
6.  void main() {
7.    T b = new T;
8.    b = p(b);
9.    b = b.f;
10. }
```

# Example: Iterative algorithm- round 4



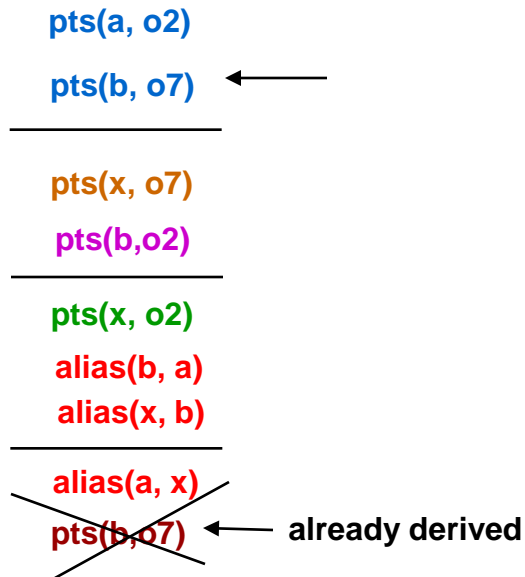
Program code:

```
1.  T p(T x) {  
2.    T a = new T;  
3.    a.f = x;  
4.    return a;  
5.  }  
6.  void main() {  
7.    T b = new T;  
8.    b = p(b);  
9.    b = b.f;  
10. }
```

Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
2. `pts(V,O) :- "V=W", pts(W,O) .`
3. `pts(V,O) :- "V=W.F", alias(W,X) "X.F=V2", pts(V2,O) .`
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# Example: Iterative algorithm- round 4



Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
2. `pts(V,O) :- "V=W", pts(W,O).`
3. `pts(V,O) :- "V=W.F", alias(W,X) "X.F=V2", pts(V2,O).`
4. `alias(W,X) :- pts(W,O), pts(X,O).`

Program code:

```
1. T p(T x) {
2.     T a = new T;
3.     a.f = x;
4.     return a;
5. }
6. void main() {
7.     T b = new T;
8.     b = p(b);
9.     b = b.f;
10. }
```



# Example: Iterative algorithm- round 4

pts(a, o2)

pts(b, o7)

---

pts(x, o7)

pts(b,o2)

---

pts(x, o2)

alias(b, a)

alias(x, b)

---

alias(a, x)

Derivation rules:

1. `pts(V,O) :- "O: V = new T".`
2. `pts(V,O) :- "V=W", pts(W,O) .`
3. `pts(V,O) :- "V=W.F", alias(W,X) "X.F=V2", pts(V2,O) .`
4. `alias(W,X) :- pts(W,O) , pts(X,O) .`

Program code:

```
1.  T p(T x) {
2.      T a = new T;
3.      a.f = x;
4.      return a;
5.  }
6.  void main() {
7.      T b = new T;
8.      b = p(b);
9.      b = b.f;
10. }
```

# Adding Context to Prolog Rules

- To add contexts to Prolog rules we can define the following predicates:
  - ◆ **pts (V, C, H)**
    - ⇒ An additional argument, representing the context, must be given to the predicate pts
  - ◆ **alias (V1, C, V2)**
    - ⇒ An additional argument, representing the context, must be given to the predicate alias
  - ◆ **formal (M, I, V)**
    - ⇒ Says that V is the i-th formal parameter declared in method M
  - ◆ **csinvokes (S, C, M, D)**
    - ⇒ Is true if the call site S in context C calls the D context of method M
  - ◆ **actual (S, I, V)**
    - ⇒ V is the i-th actual parameter used in call site S

# Example: Prolog program for context-sensitive points-to analysis

```
1. pts(V,C,H) :- "H: T V = new T()",
                csinvokes(H, C, _, _).
2. pts(V,C,H) :- "V=W", pts(W,C,H).
3. pts(V,C,O) :- "V=W.F",
                alias(W,C,X),
                "X.F=V2",
                pts(V2,C,O).
4. pts(V,D,H) :- csinvokes(S,C,M,D),
                formal(M,I,V),
                actual(S,I,W),
                pts(W,C,H).
5. alias(W,C,X) :- pts(W,C,O), pts(X,C,O).
```

- In rule 1. predicate `csinvokes(H,C,_,_)` is added in order to add information that call site H is placed in context C
- Rule 4. says that if the call site S in context C calls method M of context D, then the formal parameters in method M of context D can point to the objects pointed to by the corresponding actual parameters in context C

# Conclusions

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- An Interprocedural analysis operates across an entire program, flowing information from call sites to their callees and vice versa
- Interprocedural Analysis needs a Call Graph
- Variants of Interprocedural Analysis:
  - ◆ Context-insensitive
  - ◆ Context-sensitive:
    - ⇒ Cloning-based
    - ⇒ Inline-based
    - ⇒ Summary-based
- Key to any Interprocedural Analysis is a Points-to Analysis
  - ◆ Because it improves the precision of the call graph
- Expressing analyses as Prolog rules

# References

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- “Compilers Principles, Tehniques, & Tools” Second Edition, by Alfred Aho, Ravi Sethi, Monica Lam and Jeffrey Ullman, ISBN 0-321-48681–1, Publisher Greg Tobin
- “Everything Else About Data Flow Analysis” by Jeffrey Ullman, [infolab.stanford.edu/~ullman/dragon/w06/lectures/datalog.ppt](http://infolab.stanford.edu/~ullman/dragon/w06/lectures/datalog.ppt)
- “Why Use Datalog to Analyze Programs?” by Monica Lam, Stanford University, <http://www.springerlink.com/content/y474887q446g5052/>

# Next Talks

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- **Eda:** „Field-based and Field-Sensitive Analysis“
  - ◆ Properly modelling the flow of objects through fields
- **Saad:** „Context-Sensitive Analysis“
  - ◆ Context sensitive analysis as an extension of field-sensitive analysis
- **Obaid:** „On-the-fly call graph“
  - ◆ Dilemma: PTA needs a CG and a precise CG needs PTA ☹
- **Mohammad:** „Shape analysis“
  - ◆ More precise analyses using techniques we ignored so far the sake of efficiency