

# Chapter 7, System Design – Architecture Organization

## Object-Oriented Software Construction

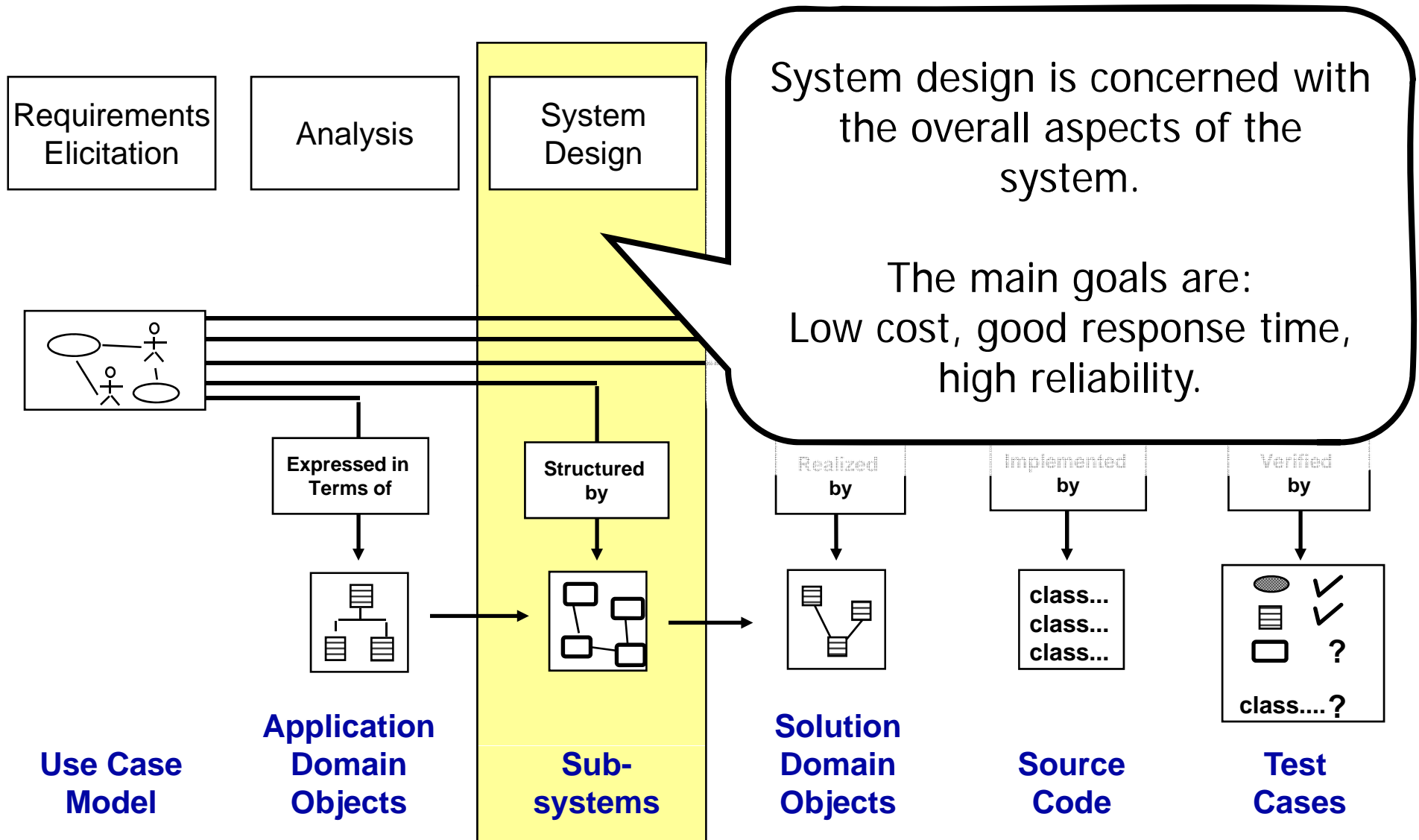
Armin B. Cremers, Tobias Rho, Daniel Speicher &  
Holger Mügge  
(based on Bruegge & Dutoit)



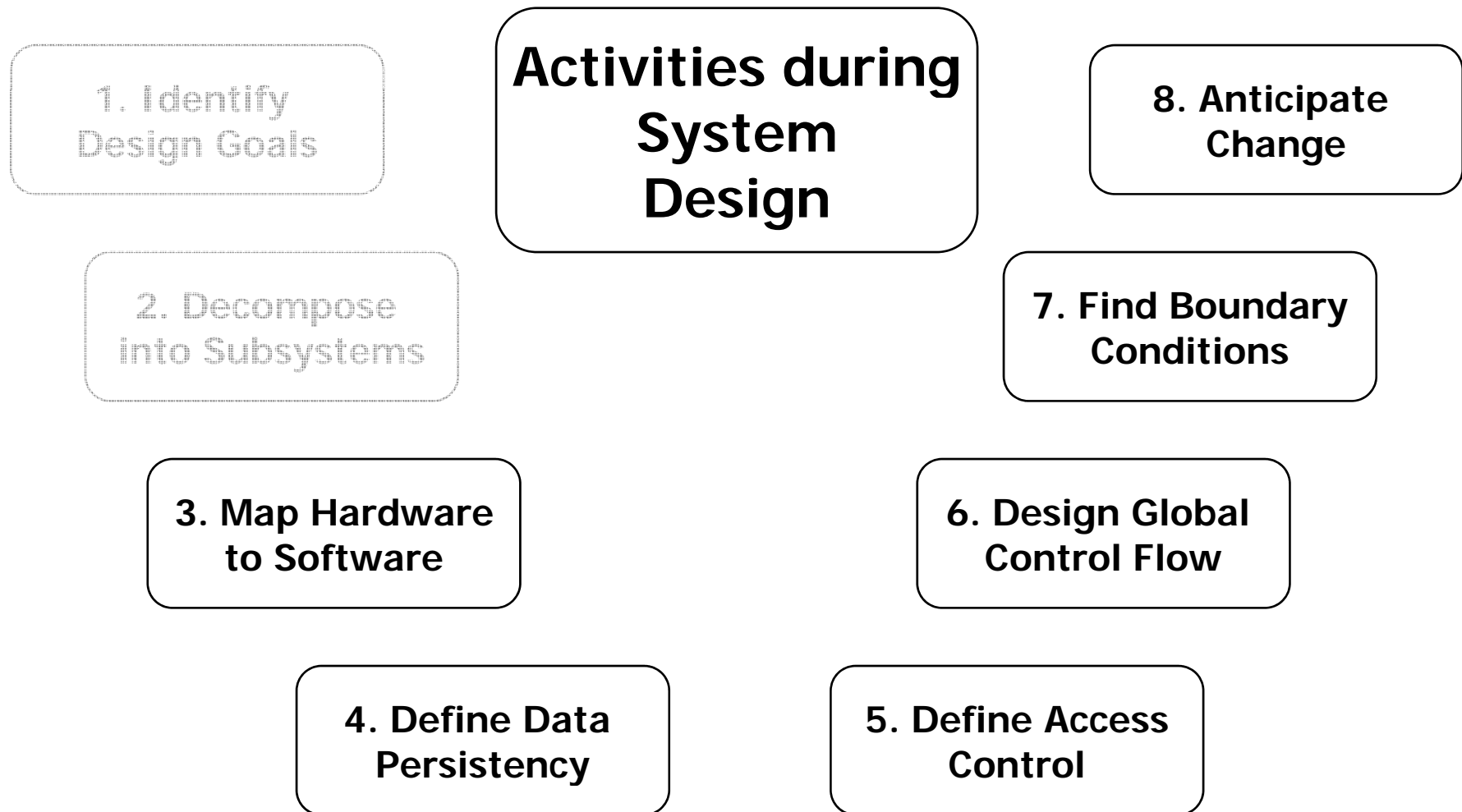
- ◆ Where are we right now? (last Lecture):
  - ◆ Overview of System Design
  - ◆ Subsystem Decomposition
    - ◆ Architectural Styles (Client-Server, Peer-to-Peer, ... )
  
- ◆ Overview of this Lecture:
  - ◆ Architecture Organization
    - ◆ Refinement of Decomposition
    - ◆ Involvement of more technical issues

# Software Lifecycle Activities

...system design



# Activities during System Design



# Aspects for Architecture Organization

- ◆ 3. Mapping of Subsystem to Hardware
  - ◆ Determine the hardware configuration
- ◆ Selection of Off-The-Shelf Components
  - ◆ Purchase existing components to realize subsystems more economically
- ◆ 4. Design of Persistent Data Management
  - ◆ Realize Storage System for objects that outlive a single execution of the system
- ◆ 5. Define Access Control
  - ◆ Protect Shared objects for concurrent access
- ◆ 6. Define Global Control flow
  - ◆ Determine the sequence of operations within the subsystems
- ◆ 7. Define Boundary Conditions
  - ◆ Determine conditions for system initialization and shut-down

# 3. Hardware Mapping

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This activity addresses two questions:

- ◆ What is the most appropriate hardware environment?
- ◆ How are objects and subsystems mapped on the chosen hardware?
  - ◆ Mapping Objects onto Reality: Processor, Memory, Input/Output
  - ◆ Mapping Associations onto Reality: Connectivity

# Hardware Mapping: Mapping the Subsystems – Important Issues

- ◆ Processor issues:
  - ◆ Is the computation rate too demanding for a single processor?
  - ◆ Can we get a speedup by distributing tasks across several processors?
  - ◆ How many processors are required to maintain steady state load?
- ◆ Memory issues:
  - ◆ Is there enough memory to buffer bursts of requests?
- ◆ I/O issues:
  - ◆ Does the response time exceed the available communication bandwidth between subsystems ?

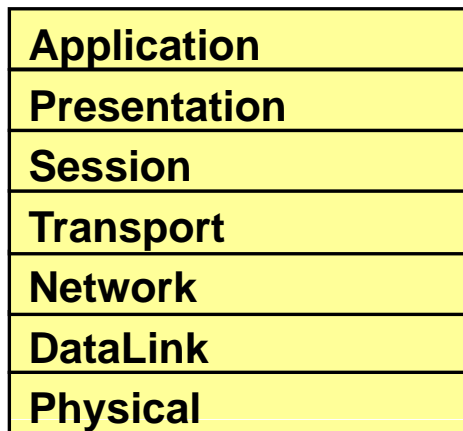
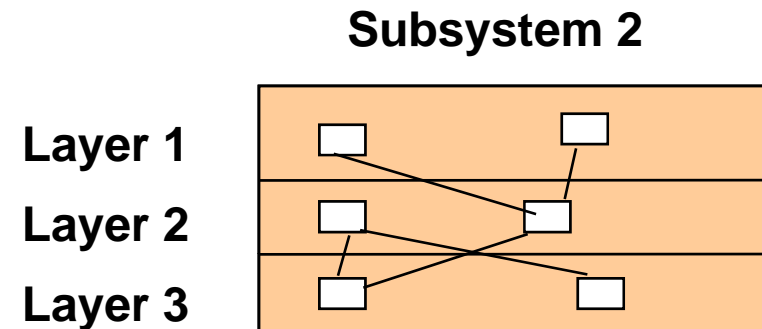
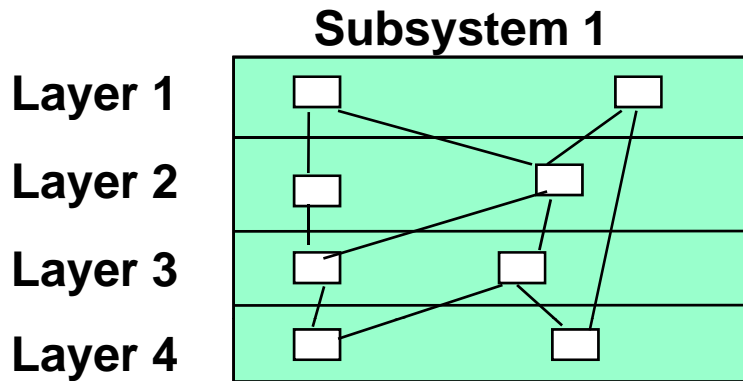
➔ Still worth considering in the 21th century ;-) ?

# Hardware Mapping: Mapping the Subsystems Associations

- ◆ Describe the *physical connectivity* of the hardware:
  - ◆ Which associations in the object model are mapped to physical connections?
  - ◆ Which of the client-supplier relationships in the analysis/design model correspond to physical connections?
  
- ◆ Describe the *logical connectivity* (subsystem associations):
  - ◆ Identify associations that do not directly map into physical connection.  
Distinction:
    - ◆ Logical Connection within a local system
    - ◆ Logical Connection within a distributed system
    - ◆ → How should these associations be implemented?

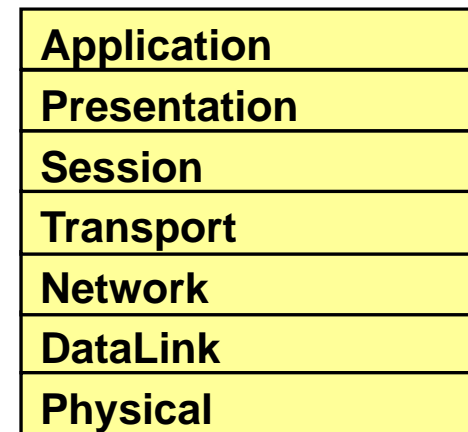


# Hardware Mapping: Logical vs. Physical Connectivity



**Processor 1**

← Bidirectional associations for each layer →



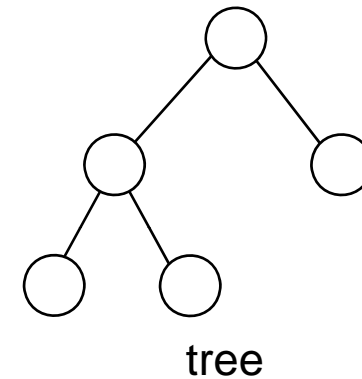
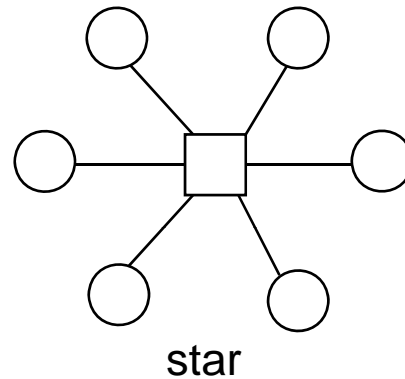
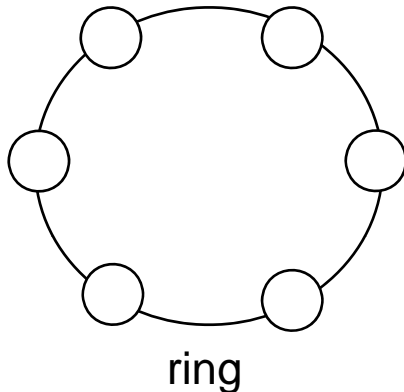
**Processor 2**

Logical Connectivity Layers

Physical Connectivity

# Hardware Mapping: Connectivity Mapping Questions

- ◆ What is the connectivity among physical units?



- ◆ What is the appropriate communication protocol between the subsystems, especially Distributed Systems?
  - ◆ Function of required bandwidth, latency and desired reliability, desired quality of service (QoS)
- ◆ Is certain functionality already available in hardware?

# Software Mapping: Selecting additional Software

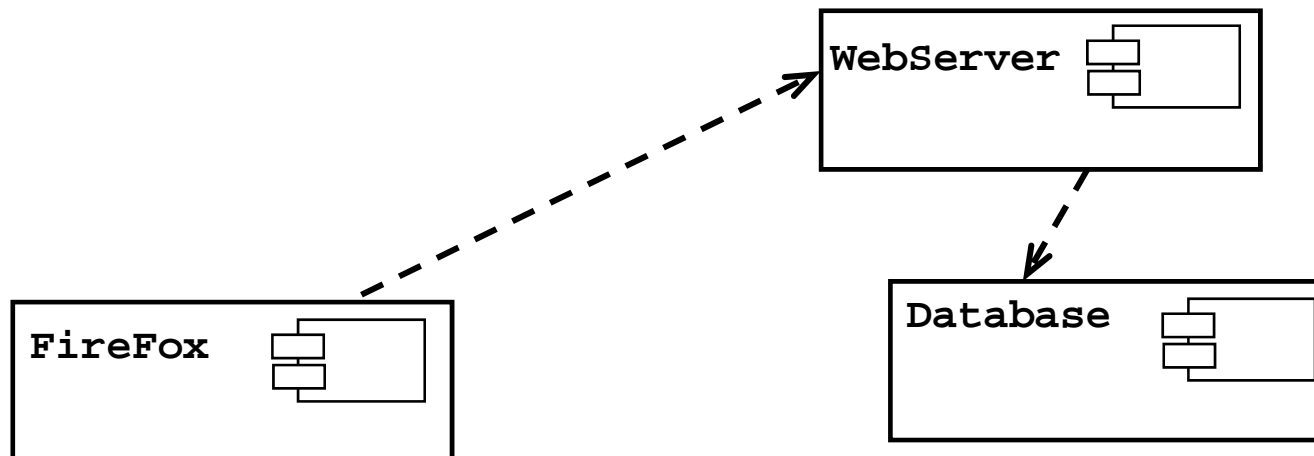
- ◆ Selection of existing software subsystems (components, services, frameworks) that realize technical aspects
  - ◆ Communication subsystems
  - ◆ Data Management subsystems
- ◆ COTS (Commercial Off-the-Shelf) Components
  - ◆ Products that are designed to be easily installed and to interoperate with existing system components.
  - ◆ Mostly no adaptation at client-side is necessary
  - ◆ Mass-produced → relatively low cost.
- ◆ Selecting a Virtual Machine:
  - ◆ Environment including operating system and any additional software components that are needed (e.g. DBMS)
  - ◆ Reduces the distance between the system and hardware
  - ◆ Reduction of development work (concentration on business code)

# Drawing Hardware/Software Mappings in UML (Excuse)

- ◆ System design must model static and dynamic structures:
  - ◆ Component Diagrams for static structures
    - ◆ show the structure at **design time** or **compilation time**
  - ◆ Deployment Diagram for dynamic structures
    - ◆ show the structure of the **run-time** system

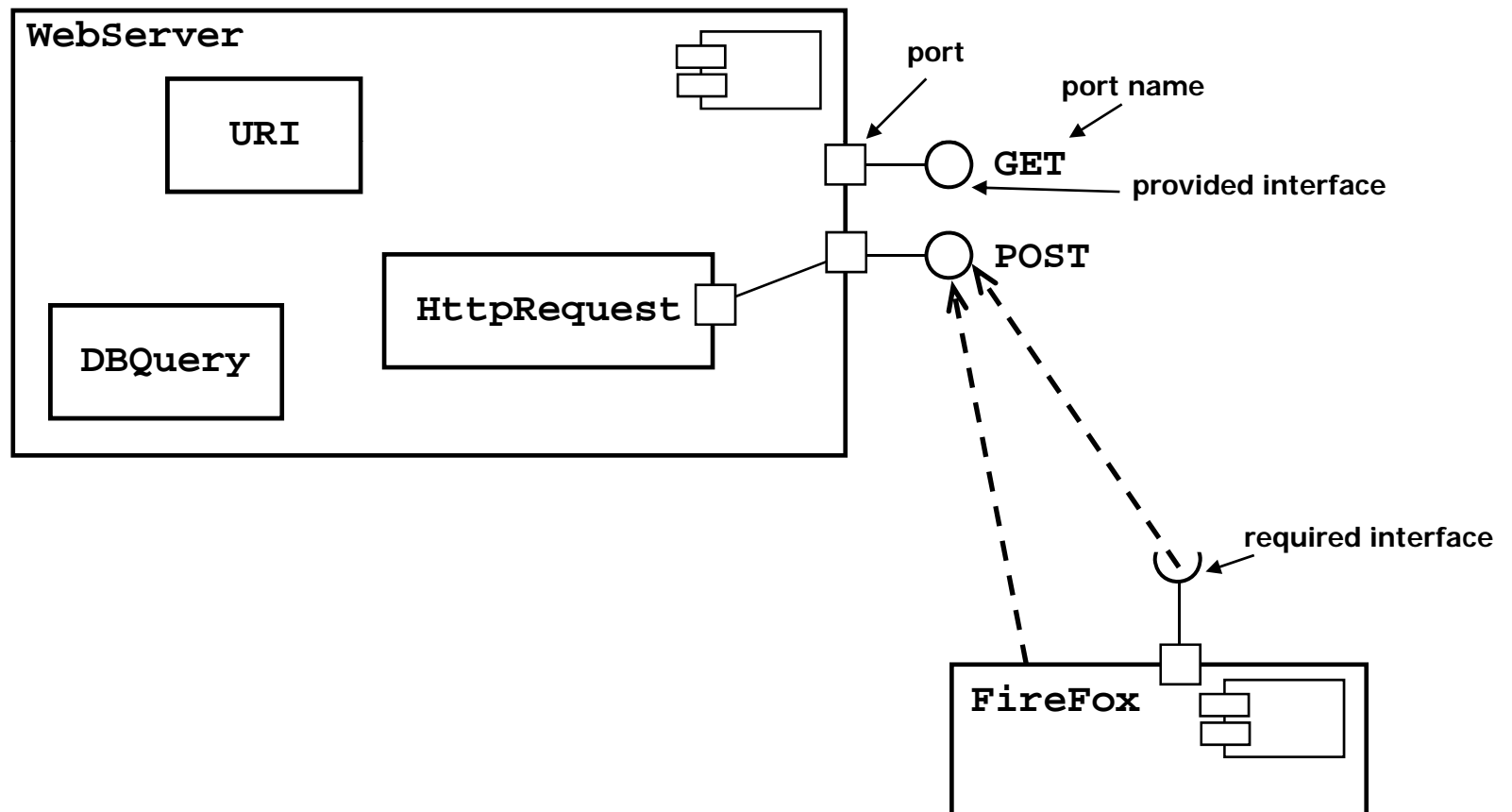
# Component Diagram

- ◆ Component Diagram (UML 2.0)
  - ◆ A graph of components connected by dependency relationships.
  - ◆ Shows the dependencies among software components
- ◆ Dependencies are shown as dashed arrows from the client component to the supplier component.



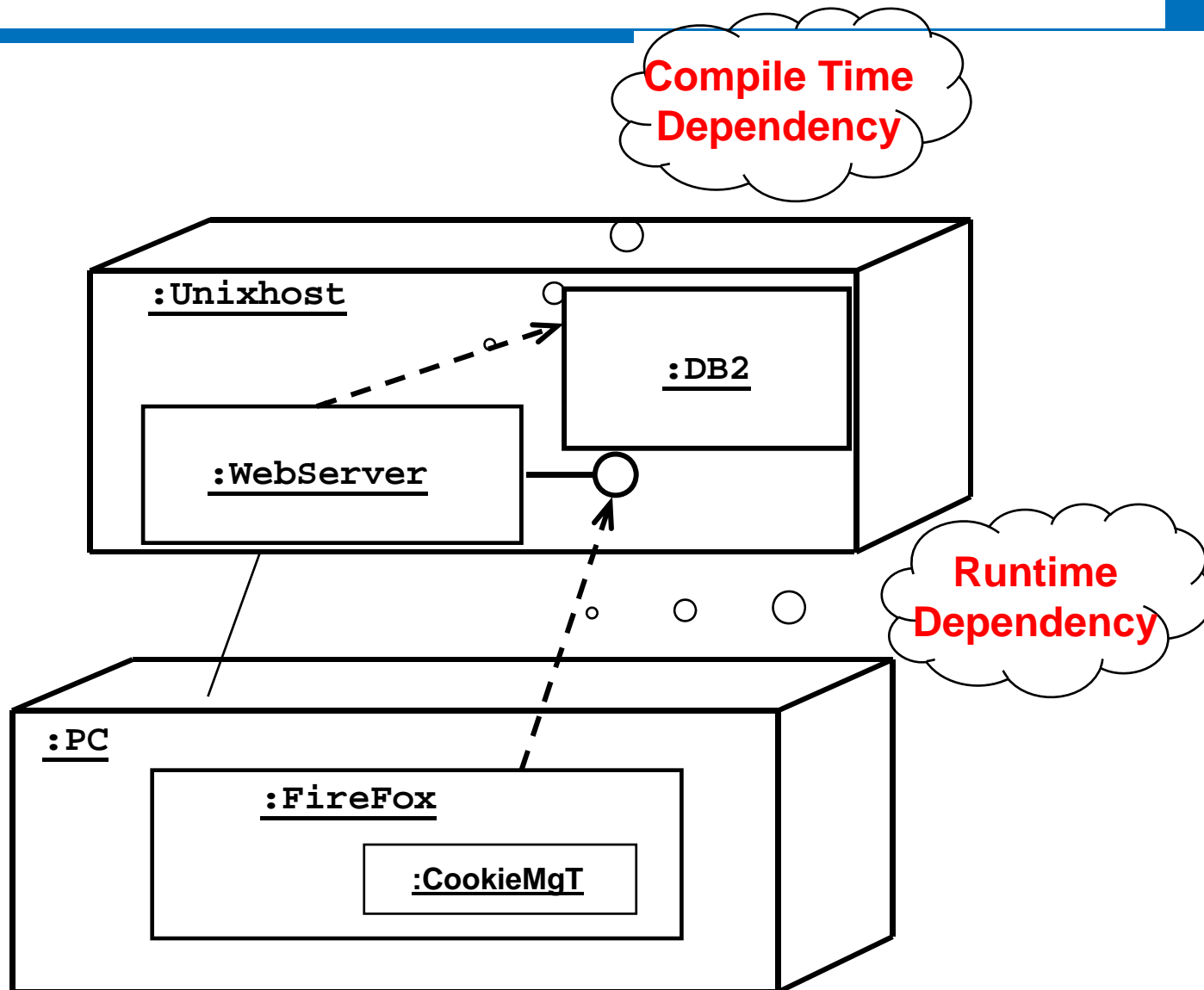
# Component Diagram

- ◆ Components can be refined to include information about the interfaces they provide (through *ports*) and the parts (classes, subsystems) they contain:



- ◆ Deployment diagrams are useful for showing a system design after the following decisions are made
  - ◆ Subsystem decomposition
  - ◆ Hardware Mapping
  - ◆ Selection of additional Software Components
- ◆ A deployment diagram is a graph of nodes connected by communication associations.
  - ◆ Nodes are shown as 3-D boxes.
  - ◆ Nodes may contain component instances.
  - ◆ Components may contain objects (indicating that the object is part of the component)

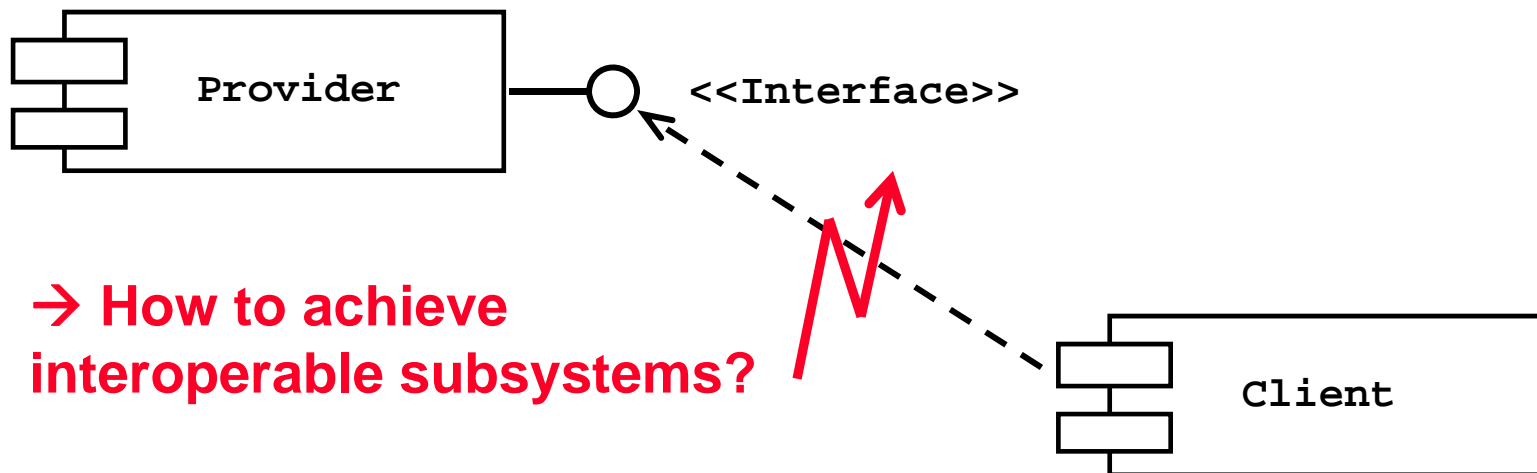
# Deployment Diagram Example





# Software Mapping: Problems with Connecting Subsystems

- ◆ Connecting subsystems yields additional problems:
  - ◆ Subsystems are implemented in different programming languages
  - ◆ The intention (semantics) cannot be derived exactly from the interface (Example: difference between POST and GET?!)
  - ◆ Subsystems might be built on different abstraction levels / communication layers



# Software Mapping: Demand: Interoperability

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- ◆ Interoperability: The ability of two or more systems or components to exchange information and to use the information that has been exchanged

**IEEE Glossary, 1990**

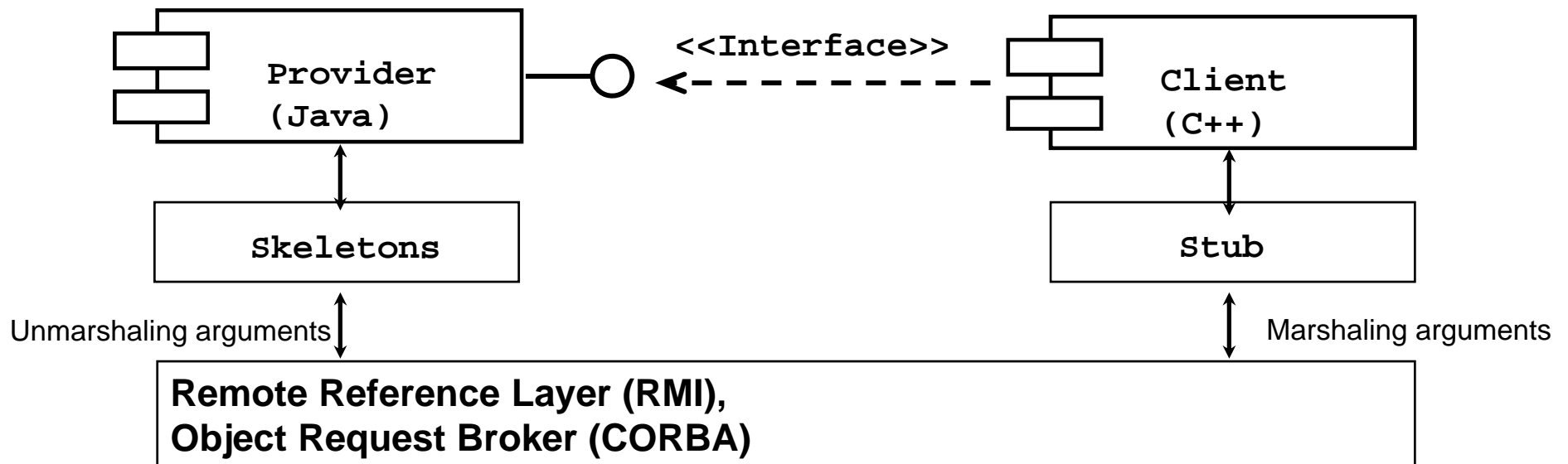
- ◆ Interoperability denote systems that work together

**Microsoft Webpage**

- ◆ In general: Use standards!
- ◆ (Selected) Requirements for interoperable Systems:
  - ◆ Standards for Communication for distributed systems
  - ◆ Semantic descriptions for interfaces
  - ◆ Mediator components

# Software Mapping: Standards for distributed systems

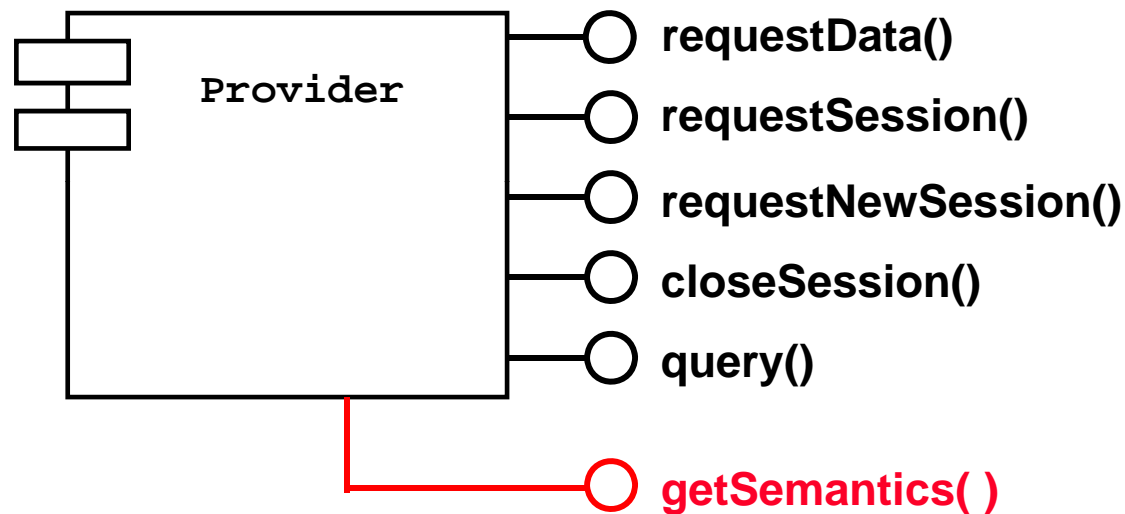
- ◆ Standards for integrating *distributed* Subsystems:
  - ◆ Middleware Frameworks (CORBA, RMI, COM, SOAP)



- ◆ Interface Definition Languages (IDL) are used to formulate Interfaces of Subsystems in an language neutral way
- ◆ Compiler transforms IDL description to concrete components (Java, C++) and generates Stubs and Skeletons

# Software Mapping: Semantic Descriptions

- ◆ Semantic Descriptions (Annotations) are instrumental to clarify the intention of a subsystem



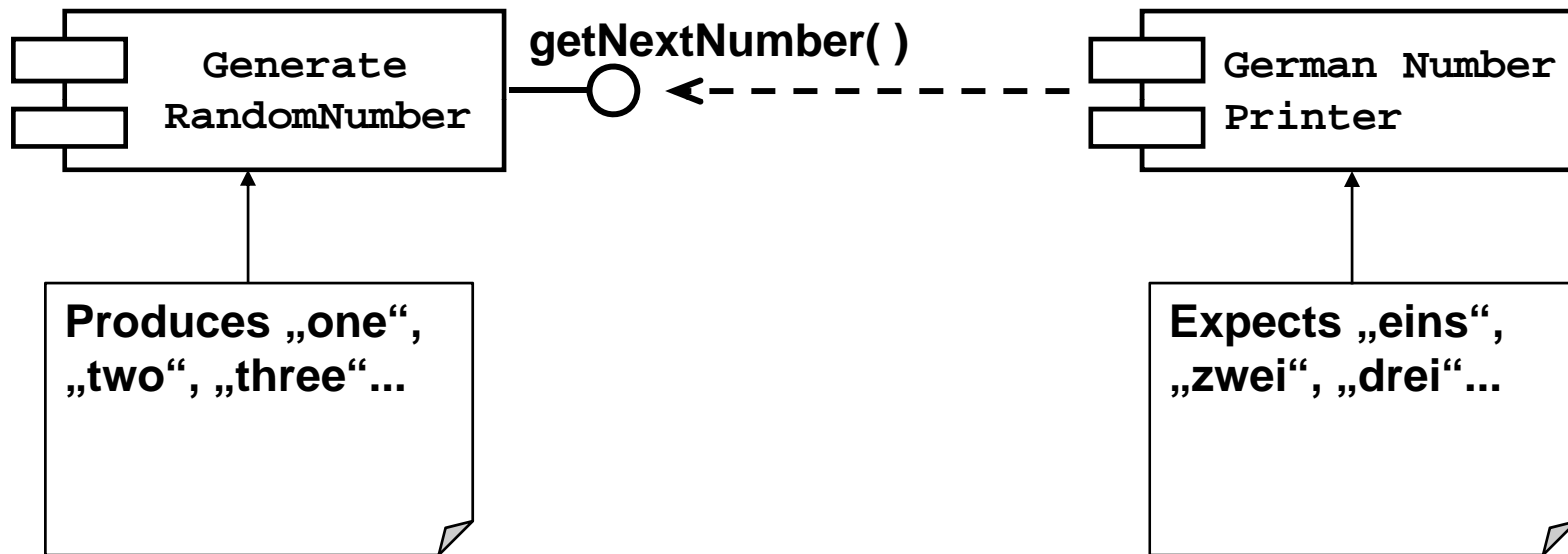
## Questions:

- Order?
- Any Iterations()?
- (Exact) Purpose?
- Dependencies?

- ◆ Hardly implemented in standard technologies, only in academic fields or in terms of proprietary solutions
- ◆ New Approach: **Ontology**: Notation for describing the semantic concepts of an interface
  - ◆ To-Date: Promising, but still hardly implemented

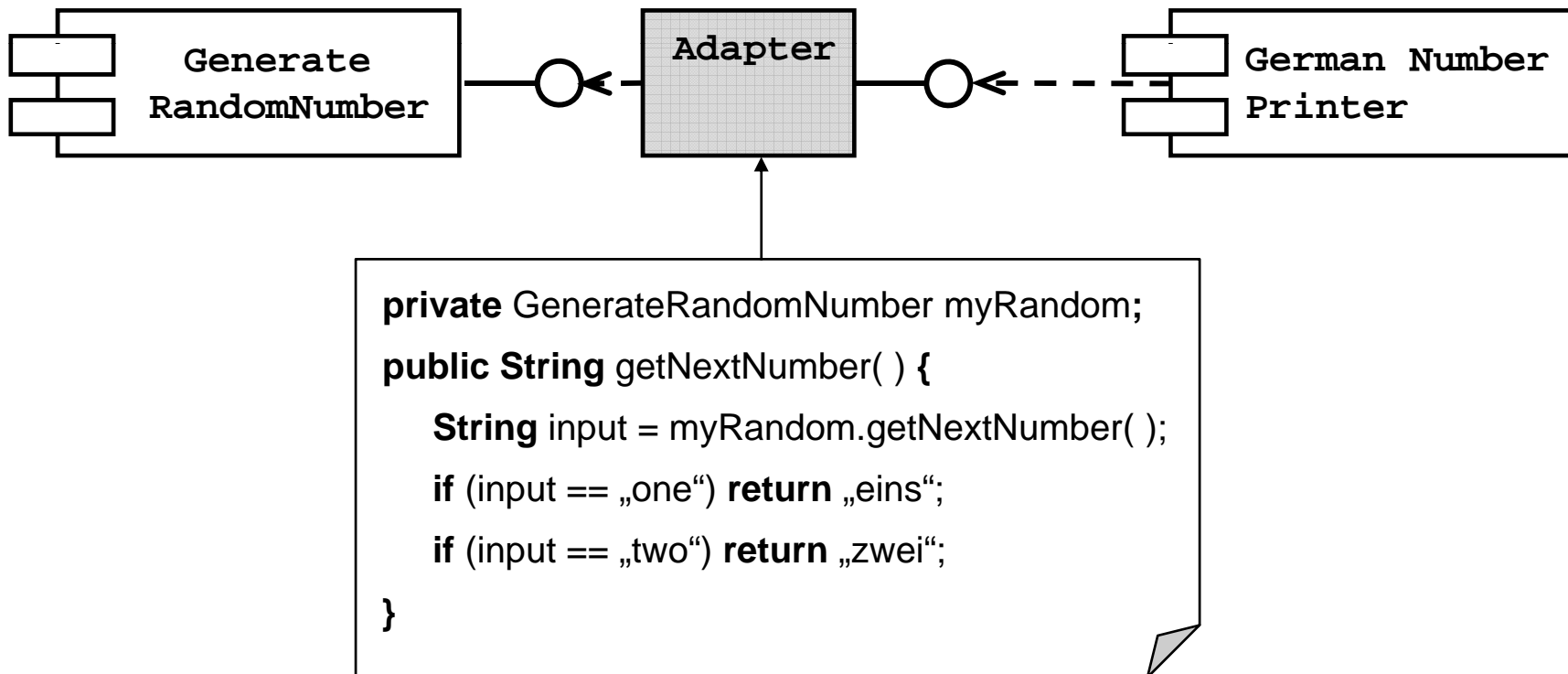
# Software Mapping: Adapters

- ◆ Problem: Incompatible Interfaces and/or different data formats (syntax):



# Software Mapping: Adapters

- ◆ Problem: Incompatible Interfaces and/or different data formats (syntax):
- ◆ Solution: Adapter (implements both interfaces and transforms data in an format, understandable for the client)



## 4. Data Management

- ◆ Some objects in the models need to be persistent
  - ◆ In particular Entity Objects
  - ◆ Boundary Objects as well (e.g. user preferences in forms)
- ◆ A persistent object can be realized with one of the following
  - ◆ Files
    - ◆ Cheap, simple, permanent storage
    - ◆ Low level (Read, Write)
    - ◆ Applications must add code to provide suitable level of abstraction
  - ◆ Database
    - ◆ Powerful, scalable, portable
    - ◆ Supports multiple writers and readers

# File or Database?

- ◆ When should you choose a file system?
  - ◆ For extensive data (images)
  - ◆ For lots of raw data (core dump, event trace)
  - ◆ Temporary Data that is kept only for a short time
  
- ◆ When should you choose a database?
  - ◆ Data that require access at fine levels of details by multiple users and/or applications (concurrent access)
  - ◆ Data that must be ported across multiple platforms (heterogeneous systems)
  - ◆ Rollback and Transactions play an important aspect



- ◆ A collection of routines that enables you to store, modify, and extract information from a database
- ◆ Main functions (realization depends on Vendor)
  - ◆ Concurrent (write) access to the stored data
  - ◆ Transaction Management
  - ◆ Rollback Mechanisms
  - ◆ Crash Recovery
  - ◆ Optimizer for complex Queries
  - ◆ Integrity Checks
  - ◆ Authorization

- ◆ Data are stored in tables that comply with a predefined type called a (relational) schema
  - ◆ Column represents an attribute of a schema
  - ◆ Row represents data item as a tuple of attribute values
  - ◆ Several tuples in different tables represent the attribute values of an object
- ◆ Mapping rules to convert object-oriented model to a relation scheme
- ◆ Ideal for querying large data sets with complex queries
- ◆ SQL is the standard language defining and manipulating tables
- ◆ Leading commercial databases:
  - ◆ DB2 (IBM)
  - ◆ Oracle
  - ◆ MySQL

- ◆ Support of all fundamental object modeling concepts
  - ◆ Stores data as objects and associations
  - ◆ Classes, Attributes, Methods, Associations, Inheritance
- ◆ Reduce the time for the initial development of storage subsystem:
  - ◆ Easy Mapping of Object model to Database schema
- ◆ Disadvantage:
  - ◆ Slower than relational databases even for simple queries
- ◆ Commercial Vendor
  - ◆ ObjectStore
  - ◆ Realization as “add-ons” for Relational DB (DB2) → Sense?
- ◆ New Hypes
  - ◆ XML Databases (mostly add-ons, many open source projects)

# 5. Defining Access Control

- ◆ In multi-user systems different actors have access to different functionality and data.
  - ◆ Example:
    - ◆ System Admin has unlimited access to any data
    - ◆ Client only has read access to data
- ◆ Definition of access right during analysis:
  - ◆ Associate different use cases with different actors.
- ◆ During system:
  - ◆ Determining which objects are shared among actors.
  - ◆ Define access rights for each objects (→ access matrix)
- ◆ Subtopics here:
  - ◆ Authentication
  - ◆ Encryption

- ◆ We model access on classes with an access matrix.
  - ◆ The rows of the matrix represents the actors of the system
  - ◆ The column represent classes whose access we want to control.
- ◆ **Access Right:** An entry in the access matrix. It lists the operations that can be executed on instances of the class by the actor.

# Access Matrix: Example

<b>Objects Actors</b>	<b>PressRelease</b>	<b>Cashflow</b>	
<b>External Organizer</b>	<b>read( )</b>		
<b>Manager</b>	<b>read( ) write( ) submit( ) Reject( )</b>	<b>read( ) compute( ) annoyAbout( )</b>	
<b>Employee</b>	<b>read( ) adjust( )</b>	<b>read( )</b>	

# Authentication and Encryption

- ◆ Authentication
  - ◆ Process of verifying the association between the identity of a user (or calling subsystem) and the system
    - ◆ User name / password
    - ◆ Smart Cards
    - ◆ Biometric Sensors (analyzing patterns of blood vessels in eyes / fingers)
- ◆ Encryption
  - ◆ Translating a message (plaintext) into an encrypted message (ciphertext).
  - ◆ A key is used to encrypt (sender) and decrypt (receiver) a message
- ◆ Both approaches are fundamentally difficult problems
  - ◆ → Select Off-the-Shelf packages !

# Different Options for Access Control

## Static:

- ◆ Global Access Tables (as shown)
- ◆ Access Control Lists (who may does what on a given object)
- ◆ Capabilities (given an actor: what can he do to what objects?)
- ◆ Rules
  - ◆ more simple to write and read

## Dynamic

- ◆ Rules
- ◆ Proxies



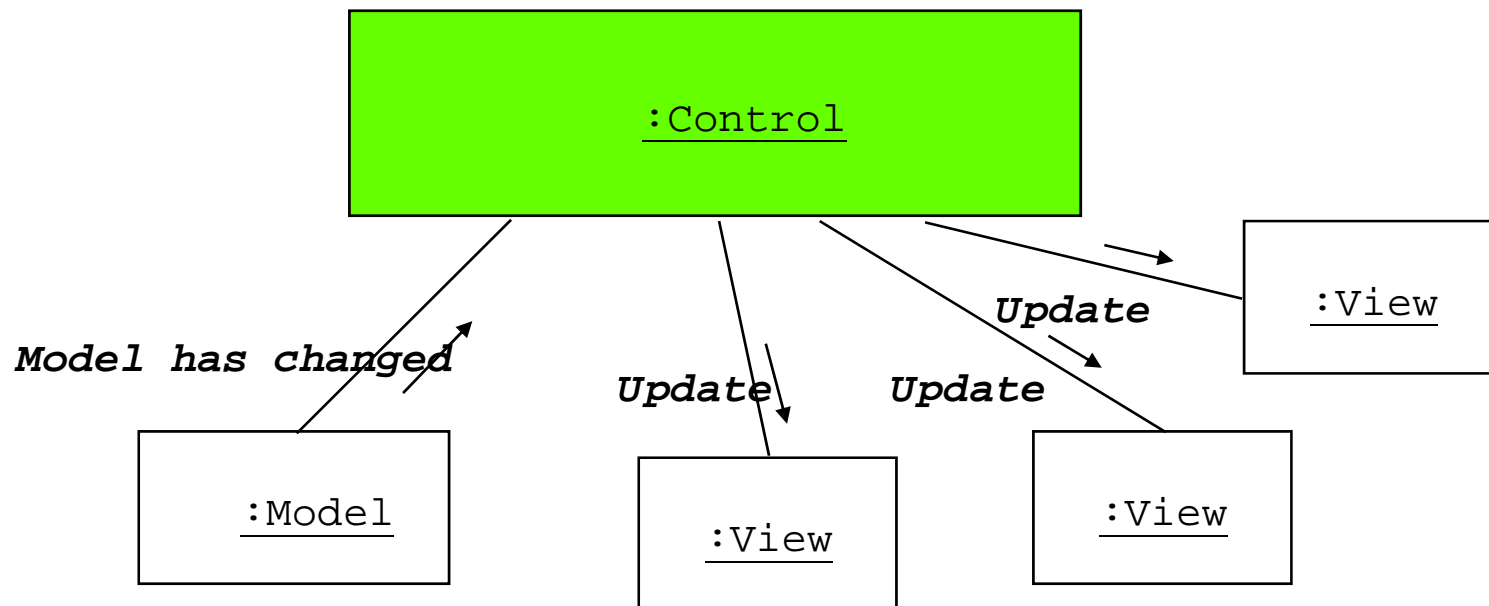
## 6. Design Global Control Flow

- ◆ Control Flow is the sequencing of actions in a system
  - ◆ Deciding which operations will be executed in which order
  - ◆ Some order is represented explicitly in the code (e.g. order of statements)
  - ◆ Some order is given implicitly by (object-oriented) language semantics (e.g. overloading, type of object decides which method version is executed)
- ◆ Control flow is modeled by control objects.
  - ◆ Record external events
  - ◆ Store temporary states about events
  - ◆ Issue the right sequence of method calls on both boundary and entity objects

- ◆ Three main control models:
  - ◆ Procedure-driven control
    - ◆ explicit
    - ◆ easy to understand (most often ... ;-) )
    - ◆ hard to change
  - ◆ Event-driven control
    - ◆ observer pattern (aka publisher subscriber)
    - ◆ callback methods in frameworks
    - ◆ somewhat implicit (you have to know where to look)
    - ◆ more flexible, reusable
  - ◆ Thread-based control
    - ◆ parallel execution (often only pseudo parallel)
    - ◆ implicit
    - ◆ sometimes difficult to understand, test, maintain
    - ◆ enable flexible UIs and non-blocking behavior in distributed systems

# Decide on Software Control

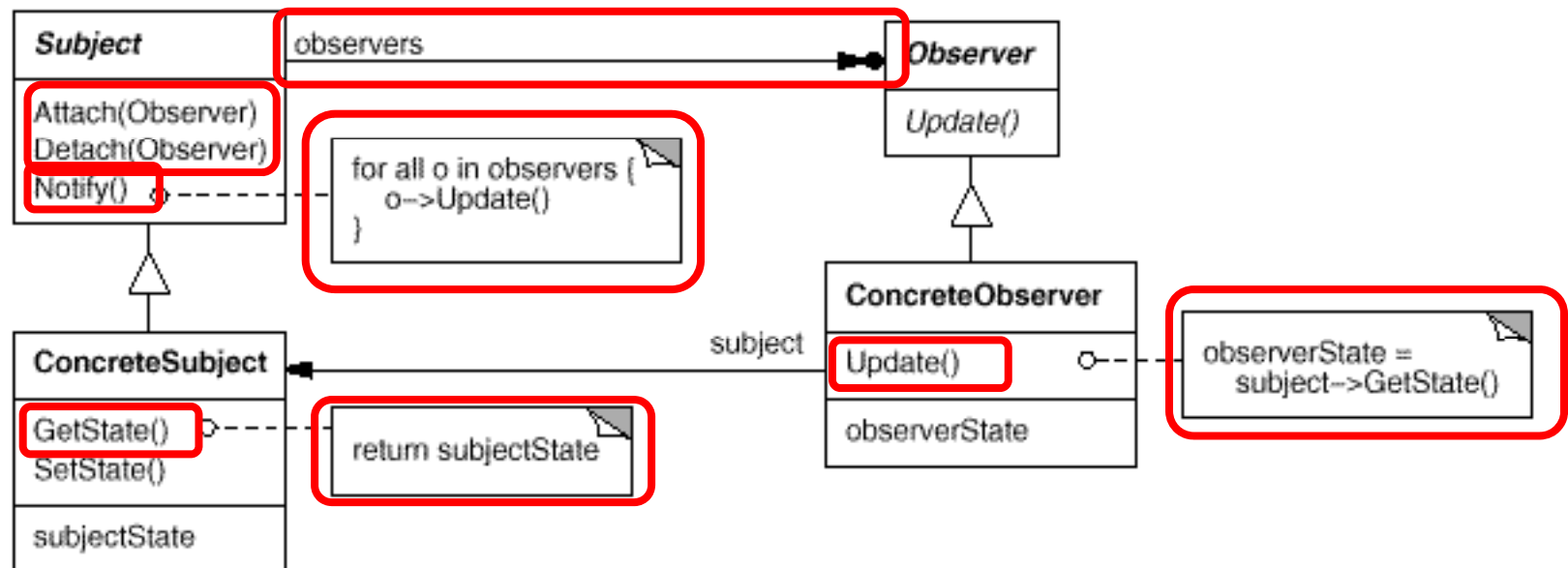
- ◆ Event-driven control
  - ◆ Control object runs a loop managing external events
    - ◆ Example (Data) Model has changed
  - ◆ Whenever an event becomes available, it is dispatched to appropriate receiver components
  - ◆ Very flexible, good for the design of graphical user interfaces, easy to extend



# Event-Driven Control Flow Observer Pattern

Two phases

1. Configuration (who observes whom)
2. Notification about changes



- ◆ Thread-based (or decentralized) control
  - ◆ Control resides in several independent objects:
    - ◆ Each external event is assigned a single Thread
    - ◆ Each new Thread handles an event
  - ◆ Possible speedup by mapping the objects on different processors

# 7. Boundary Conditions (1/2)

- ◆ Most of the system design effort is concerned with steady-state behavior.
- ◆ However, the system design phase must also address the initiation and finalization of the system. This is addressed by a set of new use cases called *administration use cases*
  - ◆ Initialization describes how the system is brought from an non initialized state to steady-state ("startup use cases").
    - ◆ How does the system start up?
    - ◆ What data need to be accessed at startup time?
    - ◆ What services have to registered?
    - ◆ What does the user interface do at start up time?
    - ◆ How does it present itself to the user?

# 7. Boundary Conditions (2/2)

## ◆ Termination

- ◆ Describes what resources are cleaned up and which systems are notified upon termination ("termination use cases").
  - Are single subsystems allowed to terminate?
  - Are other subsystems notified if a single subsystem terminates?
  - How are local updates communicated to the database?

## ◆ Failure

- ◆ Many possible causes: Bugs, errors, external problems (power supply).
- ◆ Good system design foresees fatal failures ("failure use cases").
  - How does the system behave when a node or communication link fails? Are there backup communication links?
  - How does the system recover from failure? Is this different from initialization?

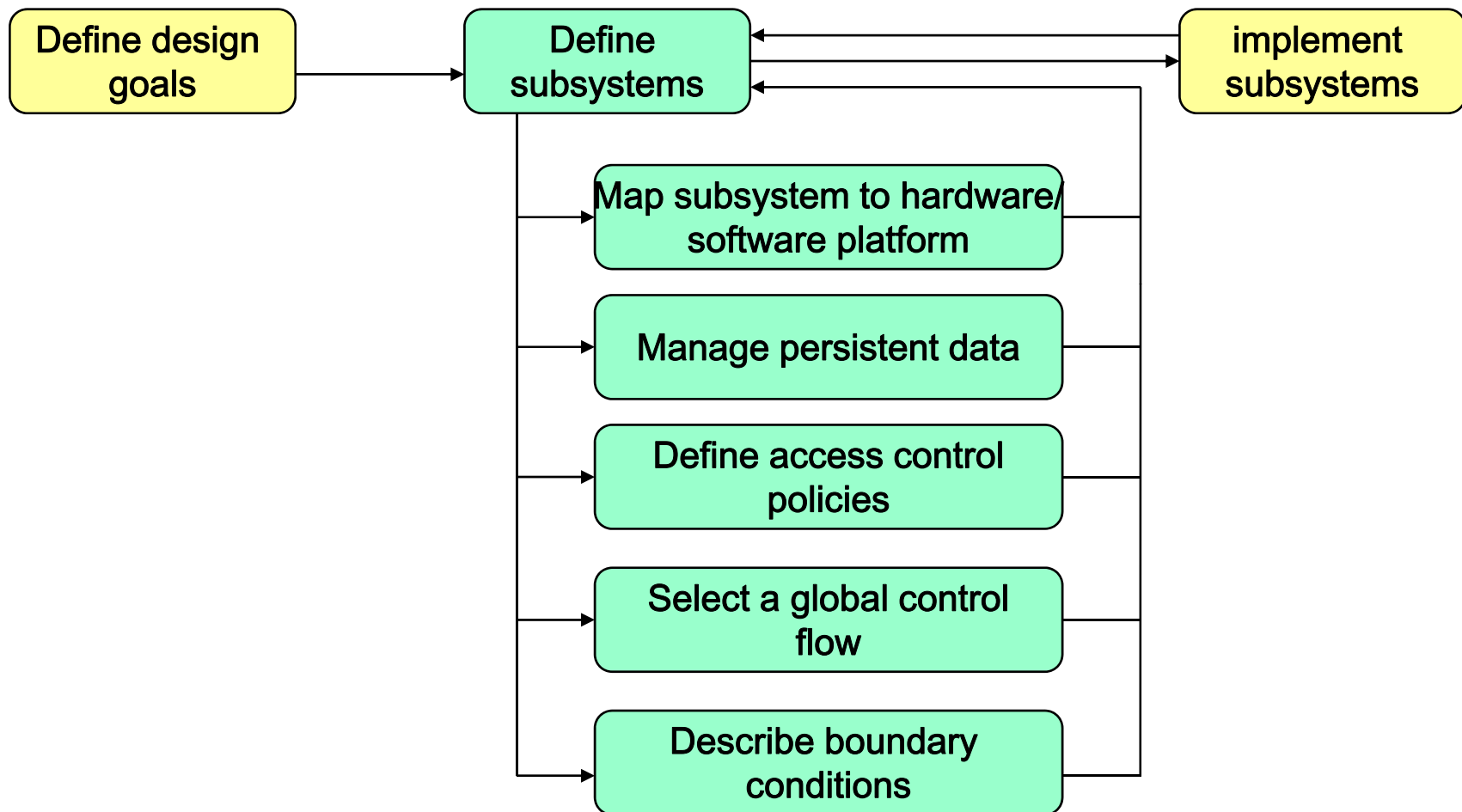
# 8. Anticipating Change

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- ◆ ... in the next lecture ...



# Architecture Organization Iterative Process



- ◆ Hardware/Software mapping
  - ◆ Persistent data management
  - ◆ Global resource handling
  - ◆ Software control selection
  - ◆ Boundary conditions
- 
- ◆ Each of these activities revises the subsystem decomposition to address a specific issue. Once these activities are completed, the interface of the subsystems can be defined.